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CS 422/522 Design & Implementation  
of Operating Systems

## Lecture 4: Memory Management & The Programming Interface

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### This lecture

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To support multiprogramming, we need “Protection”

- ◆ Kernel vs. user mode
- ◆ What is an address space?
- ◆ How to implement it?

#### Physical memory

No protection

Limited size

Sharing visible to programs

#### Abstraction: virtual memory

Each program isolated from all  
others and from the OS

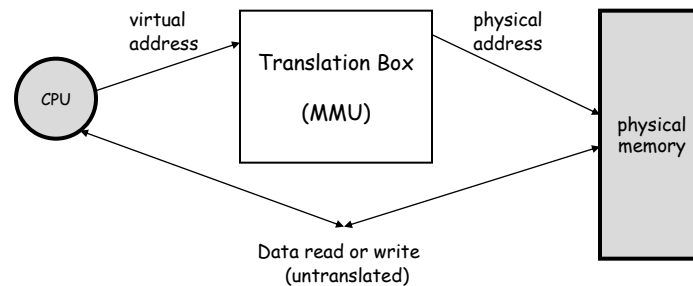
Illusion of “infinite” memory

Transparent --- can't tell if  
memory is shared

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## The big picture

- ◆ To support multiprogramming with protection, we need:
  - dual mode operations
  - translation between virtual address space and physical memory
- ◆ How to implement the translation?



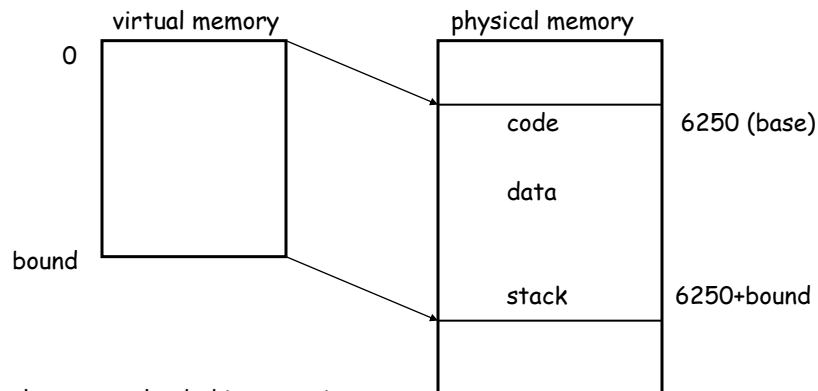
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## Address translation

- ◆ Goals
  - implicit translation on every memory reference
  - should be very fast
  - protected from user's faults
- ◆ Options
  - Base and Bounds
  - Segmentation
  - Paging
  - Multilevel translation
  - Paged page tables

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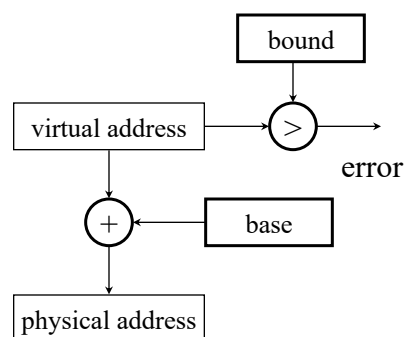
## Base and Bounds



Each program loaded into contiguous regions of physical memory.  
Hardware cost: 2 registers, adder, comparator.

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## Base and Bounds (cont' d)



- ◆ Built in Cray-1
- ◆ A program can only access physical memory in  $[base, base+bound]$
- ◆ On a context switch: save/restore base, bound registers
- ◆ Pros: Simple
- ◆ Cons: fragmentation; hard to share (code but not data and stack); complex memory allocation

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## Segmentation

### ♦ Motivation

- separate the virtual address space into several segments so that we can share some of them if necessary

### ♦ A segment is a region of logically contiguous memory

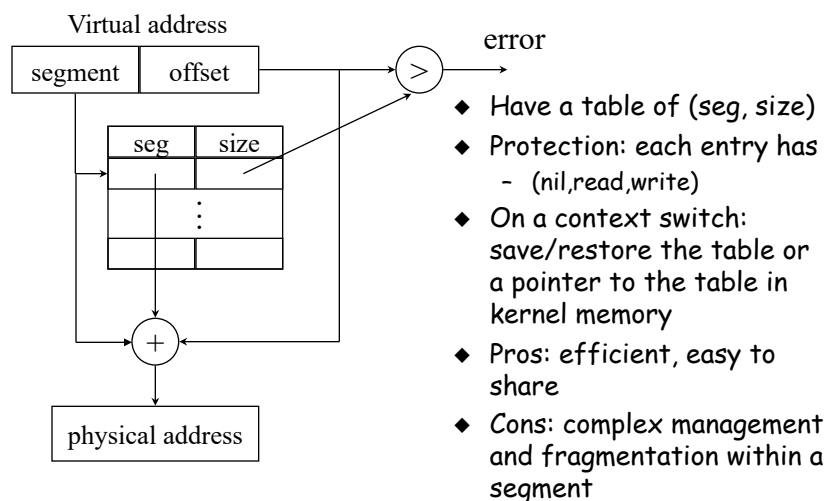
### ♦ Main idea: generalize base and bounds by allowing a table of base&bound pairs

(assume 2 bit segment ID, 12 bit segment offset)

virtual segment #	physical segment start	segment size
code (00)	0x4000	0x700
data (01)	0	0x500
- (10)	0	0
stack (11)	0x2000	0x1000

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## Segmentation (cont' d)



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## Segmentation example

(assume 2 bit segment ID, 12 bit segment offset)

v-segment #	p-segment start	segment size	physical memory	
code (00)	0x4000	0x700	0	
data (01)	0	0x500	4ff	
- (10)	0	0		
stack (11)	0x2000	0x1000	2000	
			2fff	
			4000	
			46ff	

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## Segmentation example (cont' d)

Virtual memory for strlen(x)		physical memory for strlen(x)	
Main: 240	store 1108, r2	x: 108	a b c \0
244	store pc+8, r31	...	
248	jump 360		
24c		Main: 4240	store 1108, r2
...		4244	store pc+8, r31
strlen: 360	loadbyte (r2), r3	4248	jump 360
...		424c	
420	jump (r31)	...	
...		strlen: 4360	loadbyte (r2), r3
x: 1108	a b c \0	...	
...		4420	jump (r31)
		...	

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## Paging

### ◆ Motivations

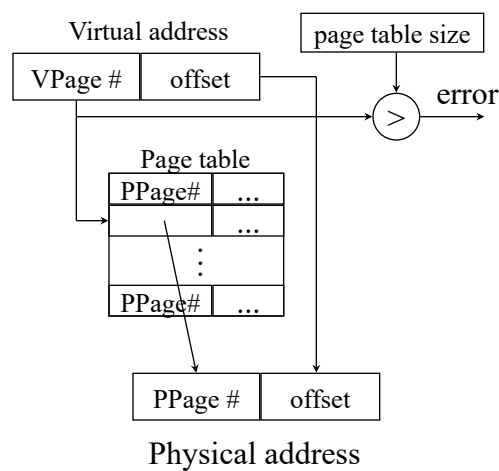
- both branch bounds and segmentation still require fancy memory management (e.g., first fit, best fit, re-shuffling to coalesce free fragments if no single free space is big enough for a new segment)
- can we find something simple and easy

### ◆ Solution

- allocate physical memory in terms of fixed size chunks of memory, or **pages**.
- Simpler because it allows use of a bitmap  
 00111110000001100 --- each bit represents one page of physical memory  
 1 means allocated, 0 means unallocated

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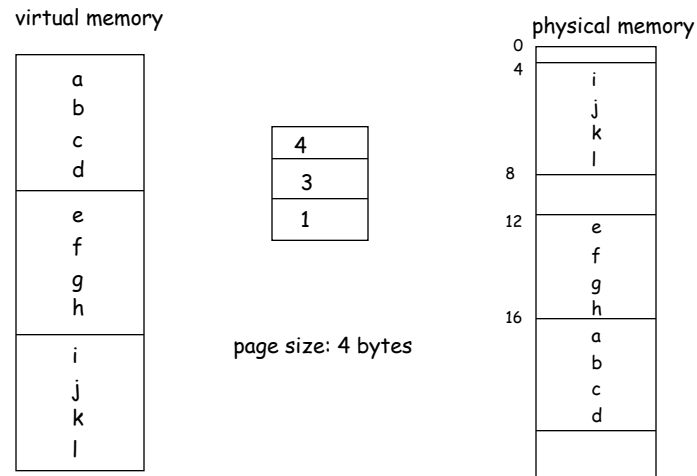
## Paging (cont' d)



- ◆ Use a page table to translate
- ◆ Various bits in each entry
- ◆ Context switch: similar to the segmentation scheme
- ◆ What should be the page size?
- ◆ Pros: simple allocation, easy to share
- ◆ Cons: big page table and cannot deal with internal fragmentation easily

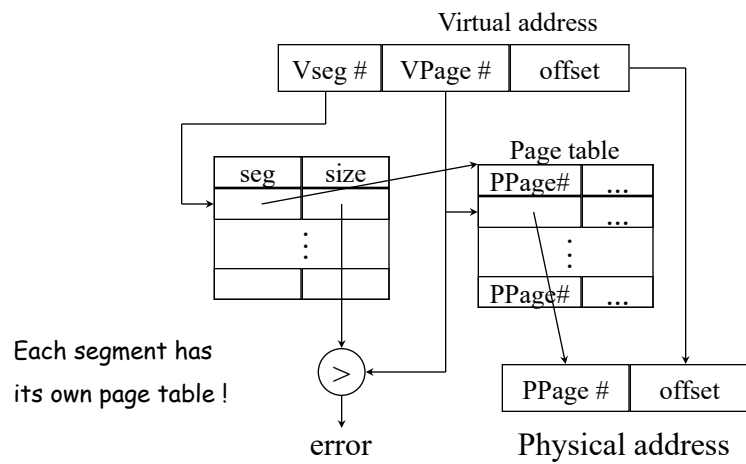
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## Paging example



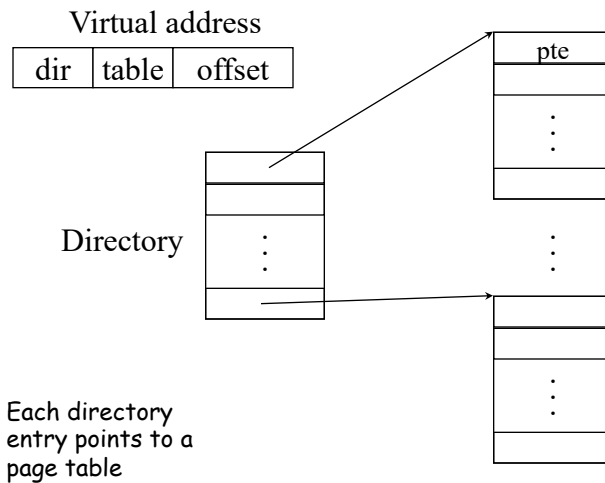
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## Segmentation with paging



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## Two-level paging



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## Two-level paging example

- ◆ A logical address (on 32-bit machine with 4K page size) is divided into:
  - a page number consisting of 20 bits.
  - a page offset consisting of 12 bits.
- ◆ Since the page table is paged, the page number is further divided into:
  - a 10-bit page number.
  - a 10-bit page offset.
- ◆ Thus, a logical address is as follows:

page number		page offset
$p_1$	$p_2$	$d$
10	10	12

where  $p_i$  is an index into the outer page table, and  $p_2$  is the displacement within the page of the outer page table.

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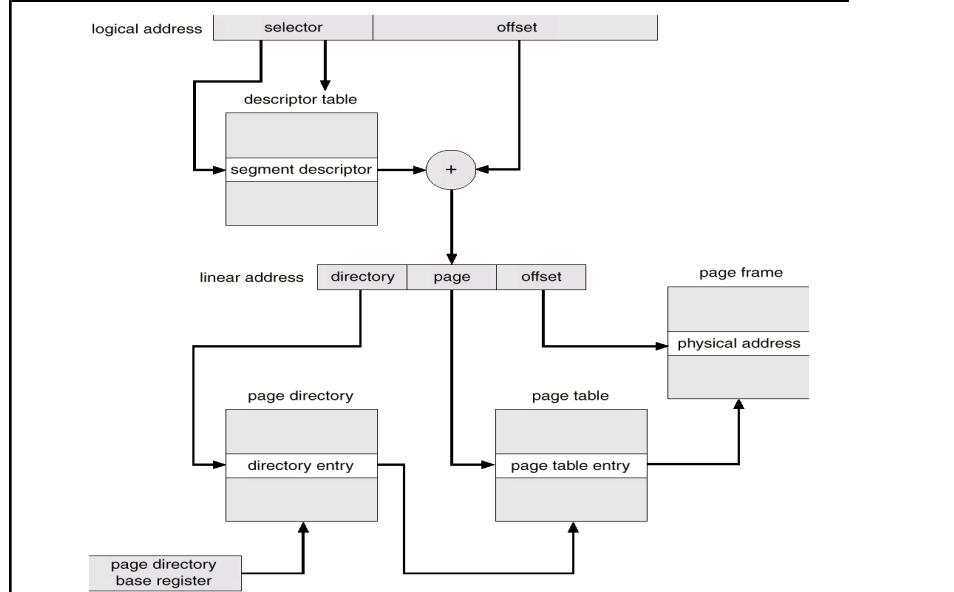


## Segmentation with paging - Intel 386

- ◆ As shown in the following diagram, the Intel 386 uses segmentation with paging for memory management with a two-level paging scheme.

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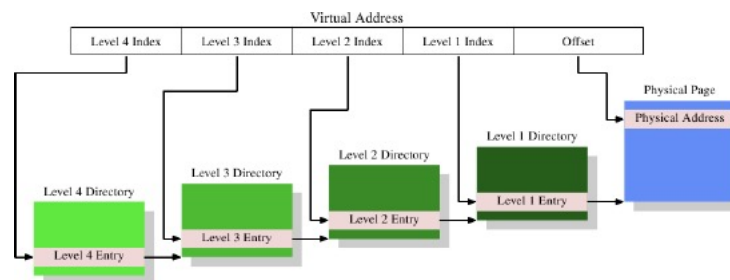
## Intel 30386 address translation



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## How many PTEs do we need ?

- ◆ Worst case for 32-bit address machine
  - # of processes  $\times 2^{20}$  (if page size is 4096 bytes)
- ◆ What about 64-bit address machine?
  - # of processes  $\times 2^{52}$



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## Summary: virtual memory mapping

- ◆ What?
  - separate the programmer's view of memory from the system's view
- ◆ How?
  - translate every memory operation using table (page table, segment table).
  - Speed: cache frequently used translations
- ◆ Result?
  - each user has a private address space
  - programs run independently of actual physical memory addresses used, and actual memory size
  - protection: check that they only access their own memory

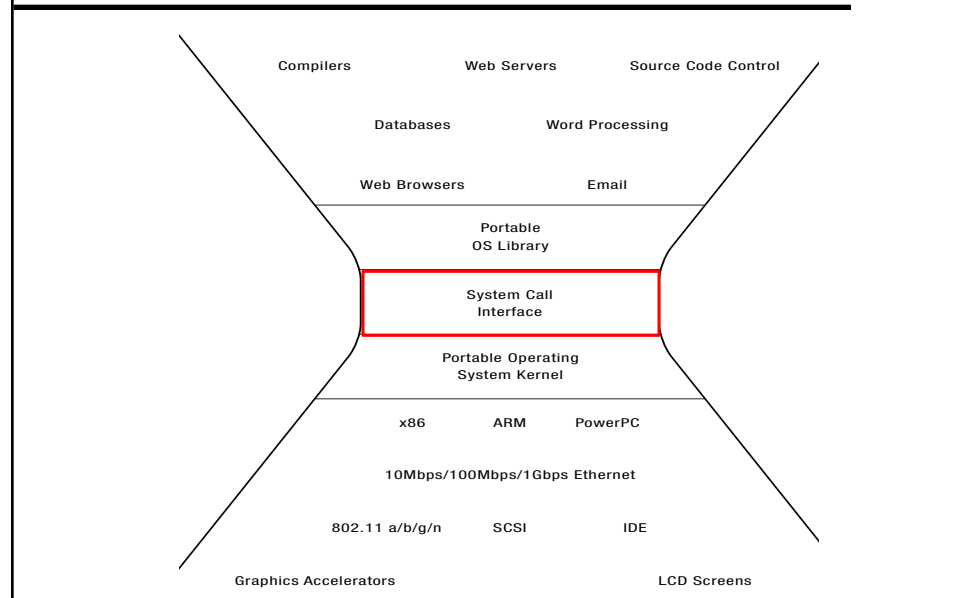
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## Summary (cont'd)

- ◆ Goal: multiprogramming with protection + illusion of "infinite" memory
- ◆ Today's lecture so far:
  - HW-based approach for protection: dual mode operation + address space
  - Address translation: virtual address → physical address
- ◆ Future topics
  - how to make address translation faster? use cache (TLB)
  - demand paged virtual memory
- ◆ The rest of today's lecture:
  - The programming interface

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## The programming interface



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## Abstraction: process & file system

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### ◆ Problem

- Multiple CPU cores, many I/O devices and lots of interrupts
- Users feel they have machine to themselves

### ◆ Answer

- Decompose hard problems into simple ones
- Deal with one at a time
- **Process is such a unit (reflecting something dynamic)**
- **File system is another high-level abstraction (for "data")**

### ◆ Future

- How processes differ from threads? What is a process really?
- Generalizing "processes" to "containers" & "virtual machines"

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## Simplest process

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### ◆ Sequential execution

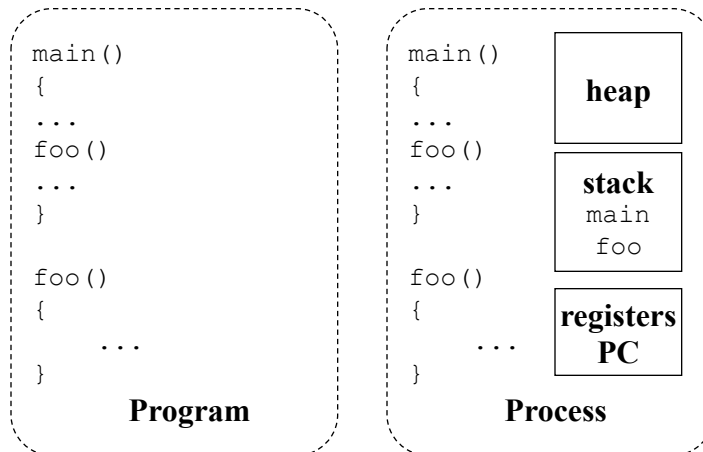
- No concurrency inside a process
- Everything happens sequentially
- Some coordination may be required

### ◆ Process state

- Registers
- Main memory
- I/O devices
  - \* File system
  - \* Communication ports

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## Program vs. process



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## Program vs. process (cont'd)

- ◆ **Process > program**
  - Program is just part of process state
  - Example: many users can run the same program (but different processes)
  
- ◆ **Process < program**
  - A program can invoke more than one process
  - Example: `cc` starts up `cpp`, `cc1`, `cc2`, `as`, `ld` (each are programs themselves)

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## Process control block (PCB)

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- ◆ Process management info
  - State
    - \* Ready: ready to run
    - \* Running: currently running
    - \* Blocked: waiting for resources
  - Registers, EFLAGS, and other CPU state
  - Stack, code and data segment
  - Parents, etc
- ◆ Memory management info
  - Segments, page table, stats, etc
- ◆ I/O and file management
  - Communication ports, directories, file descriptors, etc.
- ◆ How OS takes care of processes
  - Resource allocation and process state transition

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## Primitives of processes

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- ◆ Creation and termination
  - Exec, Fork, Wait, Kill
- ◆ Signals
  - Action, Return, Handler
- ◆ Operations
  - Block, Yield
- ◆ Synchronization
  - We will talk about this later

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## Make a process

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- ◆ Creation
  - Load code and data into memory
  - Create an empty call stack
  - Initialize state to same as after a process switch
  - Make the process ready to run
- ◆ Clone
  - Stop current process and save state
  - Make copy of current code, data, stack and OS state
  - Make the process ready to run

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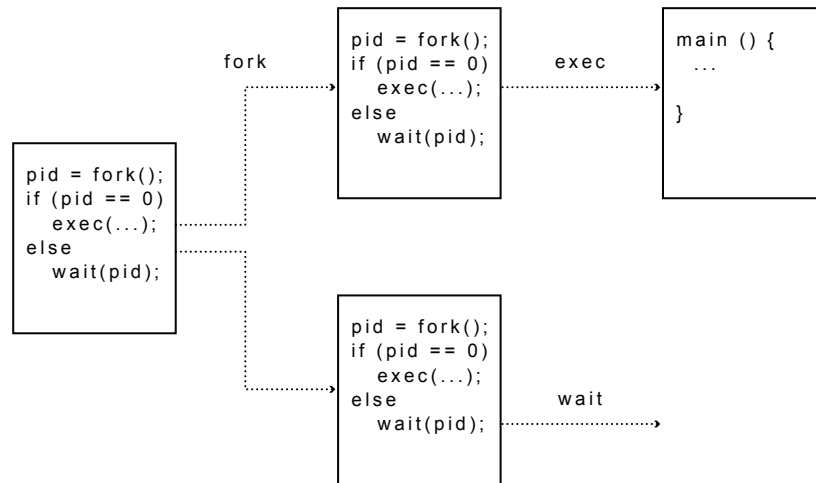
## UNIX process management

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- ◆ UNIX **fork** - system call to create a copy of the current process, and start it running
  - No arguments!
- ◆ UNIX **exec** - system call to change the program being run by the current process
- ◆ UNIX **wait** - system call to wait for a process to finish
- ◆ UNIX **signal** - system call to send a notification to another process

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## UNIX process management



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## Question: What does this code print?

```

int child_pid = fork();

if (child_pid == 0) {      // I'm the child process
    printf("I am process #%d\n", getpid());
    return 0;
} else {                  // I'm the parent process
    printf("I am parent of process #%d\n", child_pid);
    return 0;
}

```

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## Implementing UNIX fork & exec

- ◆ Steps to implement UNIX fork
  - Create and initialize the process control block (PCB) in the kernel
  - Create a new address space
  - Initialize the address space with a copy of the entire contents of the address space of the parent
  - Inherit the execution context of the parent (e.g., any open files)
  - Inform the scheduler that the new process is ready to run
- ◆ Steps to implement UNIX exec
  - Load the program into the current address space
  - Copy arguments into memory in the address space
  - Initialize the hardware context to start execution at ``start``

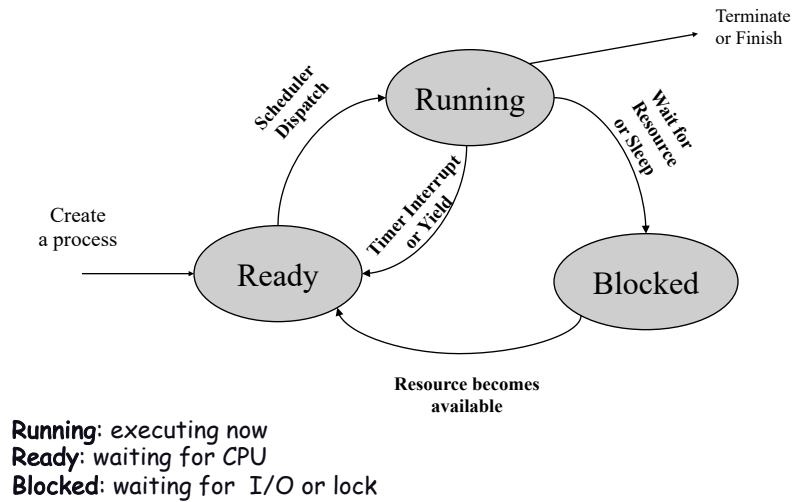
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## Process context switch

- ◆ Save a context (everything that a process may damage)
  - All registers (general purpose and floating point)
  - All co-processor state
  - Save all memory to disk? *Very machine dependent!*
  - What about cache and TLB stuff?
- ◆ Start a context
  - Does the reverse
- ◆ Challenges
  - OS code must save state without changing any state
  - How to run without touching any registers?
    - \* CISC machines have a special instruction to save and restore all registers on stack
    - \* RISC: reserve registers for kernel or have way to carefully save one and then continue

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## Process state transition



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## Which ready process to pick?

0 ready processes: run idle loop

1 ready process: easy!

> 1: what to do?

◆ FIFO?

- put threads on back of list, pull them off from front
- (nachos does this: `schedule.cc`)

◆ Pick random? (could result in starvation)

◆ Priority?

- give some threads a better shot at the CPU

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## Scheduling policies

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- ◆ Scheduling issues
  - fairness: don't starve process
  - prioritize: more important first
  - deadlines: must do by time 'x' (car brakes)
  - optimization: some schedules >> faster than others
- ◆ No universal policy:
  - many variables, can't maximize them all
  - conflicting goals
    - \* more important jobs vs starving others
    - \* I want my job to run first, you want yours.
- ◆ Given some policy, how to get control ?

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## How to get control?

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- ◆ Traps: events generated by current process
  - system calls
  - errors (illegal instructions)
  - page faults
- ◆ Interrupts: events external to the process
  - I/O interrupt
  - timer interrupt (every 100 milliseconds or so)
- ◆ Process perspective:
  - explicit: process yields processor to another
  - implicit: causes an expensive blocking event, gets switched

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## UNIX I/O --- a key innovation ("files")

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- ◆ Uniformity
  - All operations on all files, devices use the same set of system calls: open, close, read, write
- ◆ Open before use
  - Open returns a handle (file descriptor) for use in later calls on the file
- ◆ Byte-oriented
- ◆ Kernel-buffered reads/writes
- ◆ Explicit close
  - To garbage collect the open file descriptor
- ◆ Pipes (for interprocess communication → a kernel buffer with two file descriptors, one for reading, one for writing)

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## UNIX file system interface

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- ◆ UNIX file open is a Swiss Army knife:
  - Open the file, return file descriptor
  - Options:
    - \* If file doesn't exist, return an error
    - \* If file doesn't exist, create file and open it
    - \* If file does exist, return an error
    - \* If file does exist, open file
    - \* If file exists but isn't empty, nix it then open
    - \* If file exists but isn't empty, return an error
    - \* ...

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