

# CERTIFIED INTERRUPTIBLE OS KERNELS AND DEVICE DRIVERS

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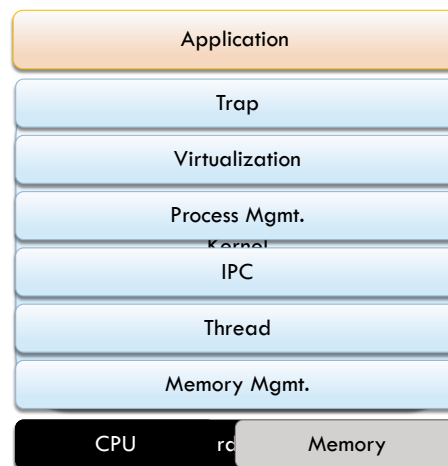
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## Formal Verification of OS Kernel

□ seL4

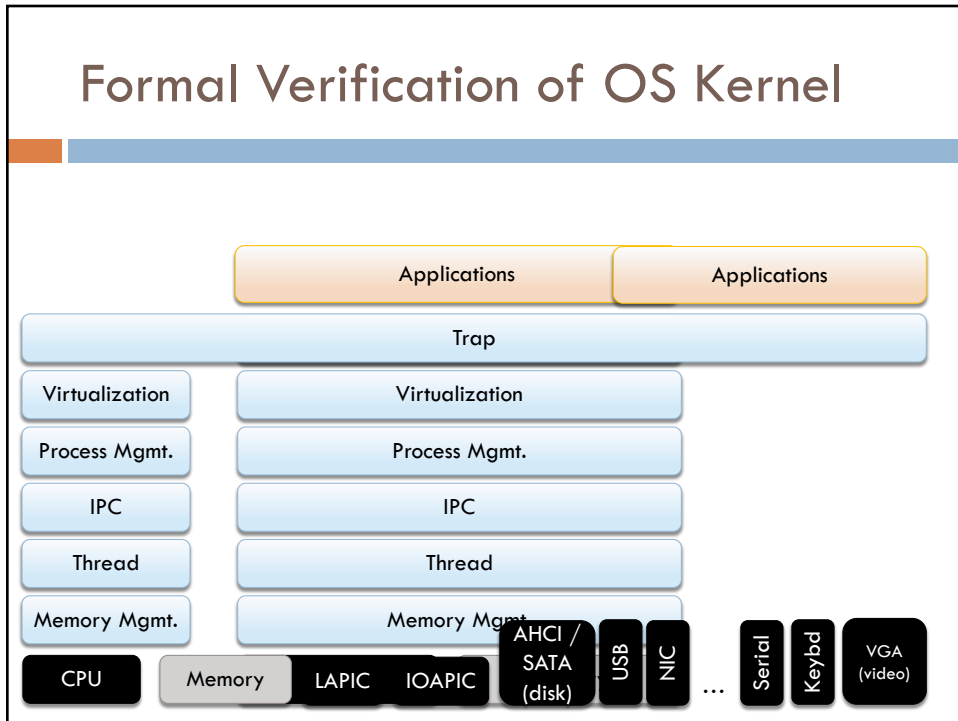
□ CertiKOS

□ Verve



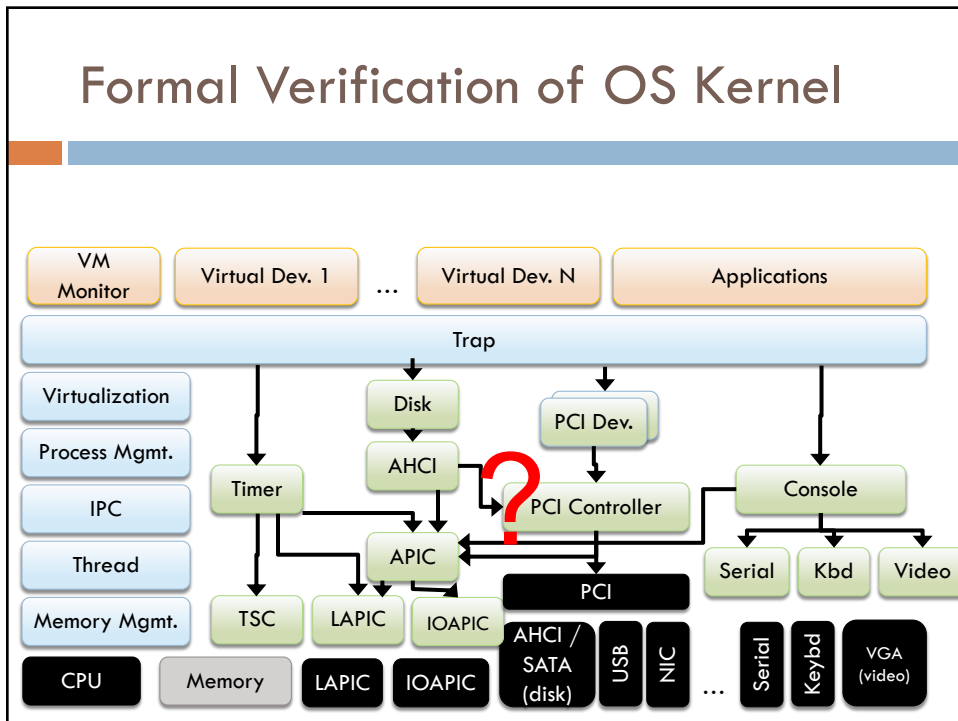
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# Formal Verification of OS Kernel



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# Formal Verification of OS Kernel



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# Device Drivers in Mainstream OS

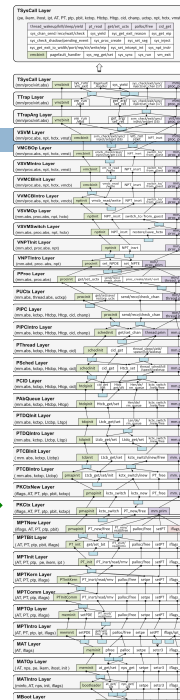
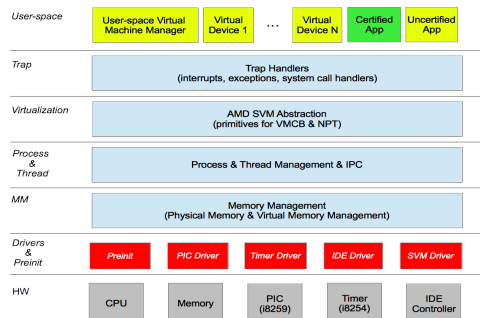
- 70% of Linux 2.4.1 kernel are device drivers.
- 70% of Windows crash are caused by third-party driver code.



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# mCertiKOS Overview [POPL'15]

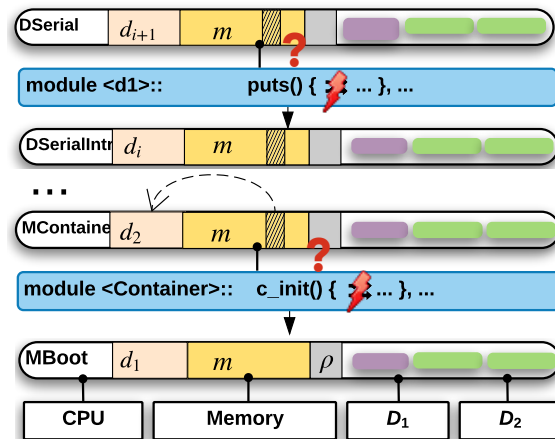
- Single-core version of CertiKOS.
- 3k LOC, can boot Linux as guest.
- Aggressive use of abstraction over deep specification (37 layers).



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## Main Challenge

Every fine-grained processor step could be interrupted.



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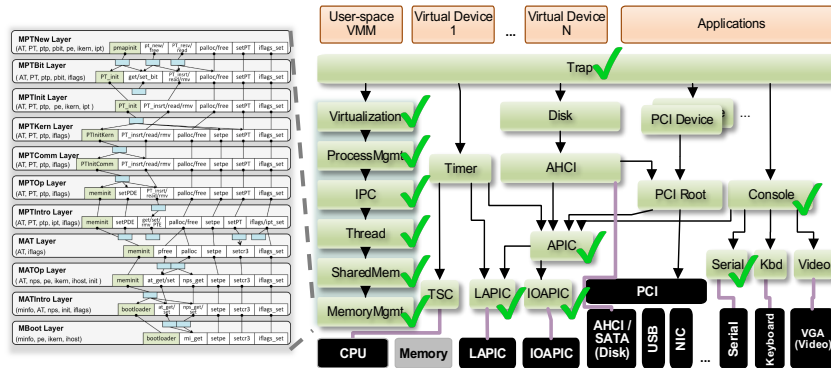
## Other Challenges

- ▣ Interrupt hardware can be *dynamically* configured.
- ▣ Devices and CPU run in *parallel*.
- ▣ Device drivers are written in both C and *assembly*.
- ▣ The correctness results of different components should be *linked formally*.

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## Our Contributions [PLDI'16]

The *first* formally verified *interruptible* OS kernel with *device drivers*.



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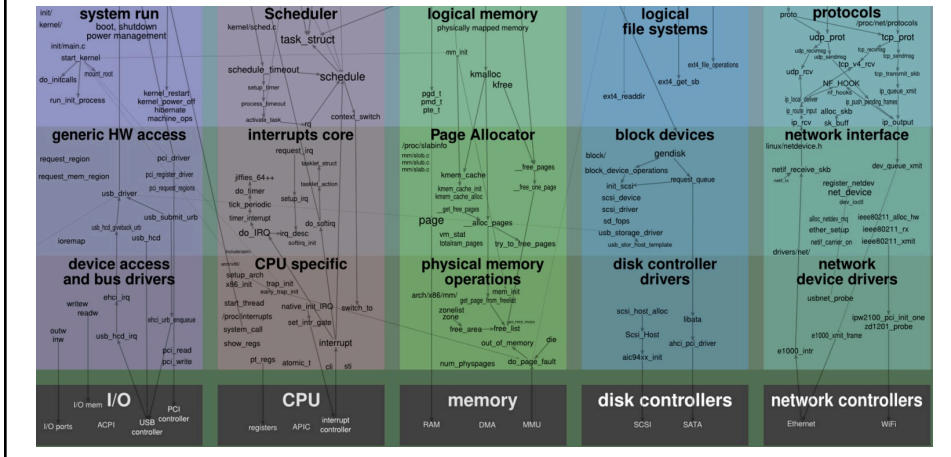
## Our Contributions [PLDI'16]

- New techniques for certifying abstraction layers with multiple *logical CPUs* and devices.
- New techniques for building formal *certified device hierarchies*.
- An abstraction-layer-based approach for reasoning about *interrupts*.
- **Case study:** interruptible mCertikOS with device drivers.

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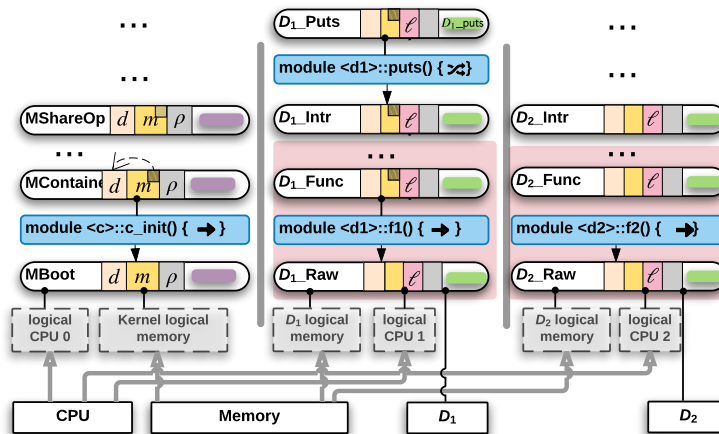
# Linux Kernel Map

Kernel components are sorted into different stacks of abstraction layers based on their underlying hardware device.



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# New Machine Model



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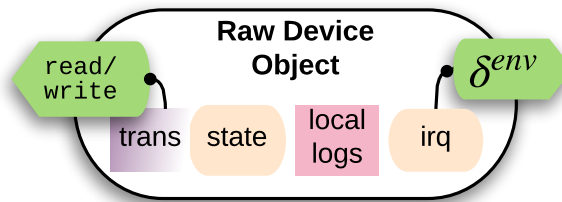
## Hardware Device Model

- ▣ Devices are modeled as transition systems parameterized by all possible lists of external events.
- ▣ Example external events:
  - ▣ Recv (s: list char)
  - ▣ KeyPressed (c: Z)
- ▣ State: observable registers.
- ▣ Transition:
  - ▣ environmental transition:  $\delta^{\text{env}}$
  - ▣ I/O transition:  $\delta^{\text{CPU}}$

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## Raw Device Object

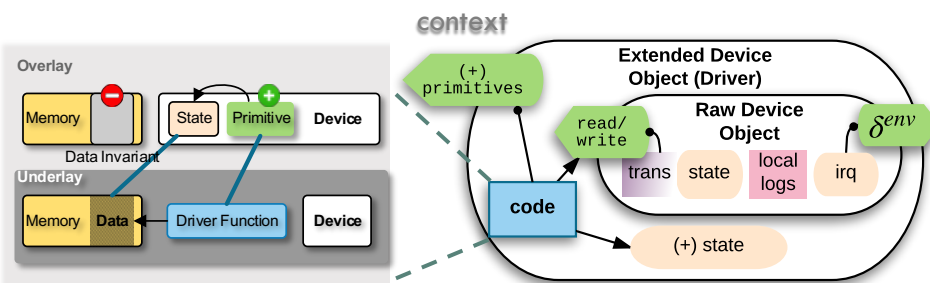
- Local log for the list of observed external events.
- Multiple local logs to handle disjoint set of external events asynchronously.
- Read/Write instructions: IN/OUT, memory mapped I/O, etc.



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## Extended Device Object

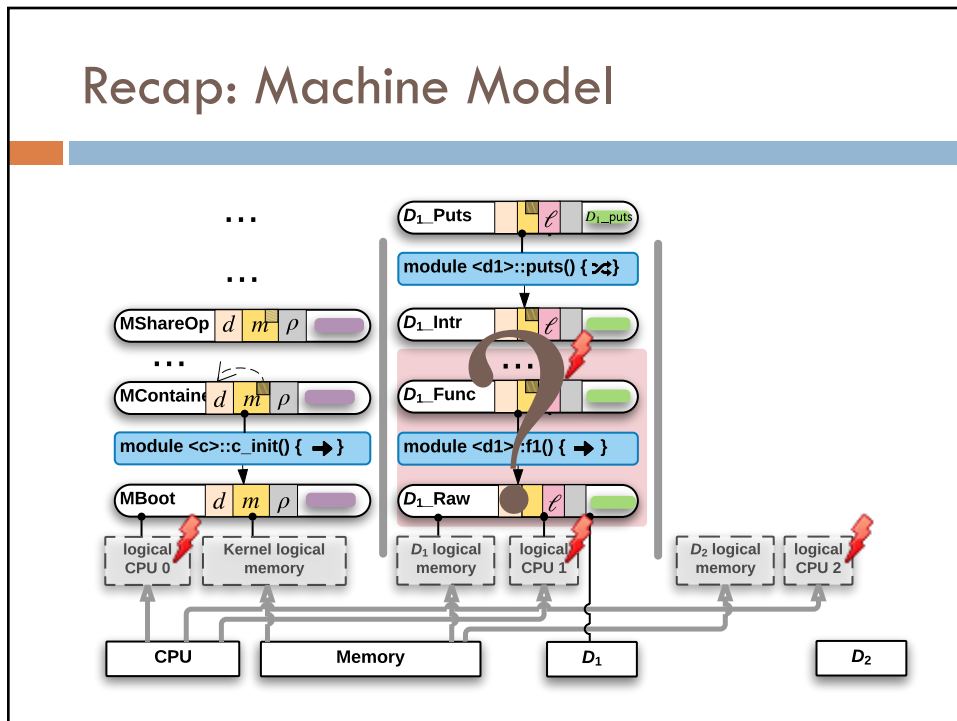
Driver as a logical device.



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## Recap: Machine Model



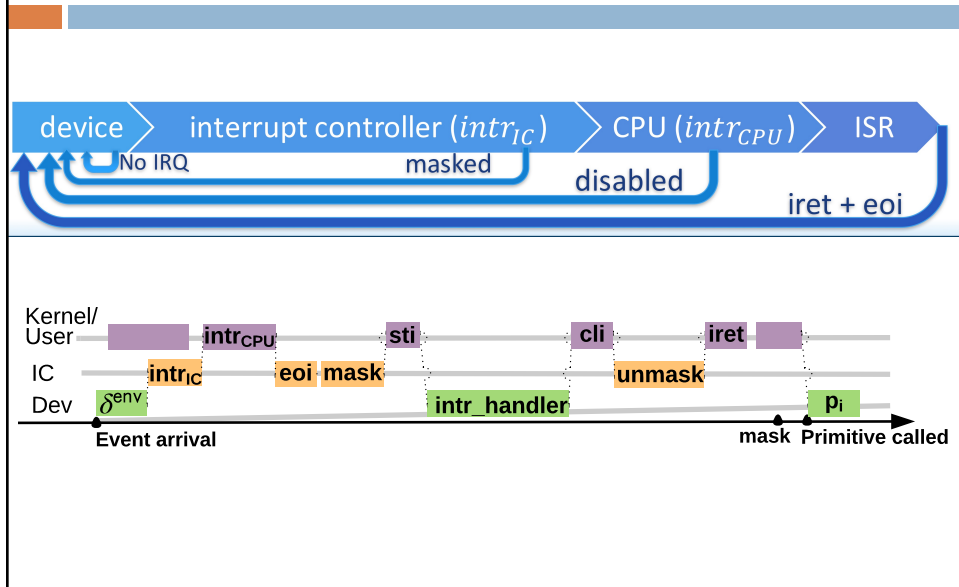
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## Our Contributions

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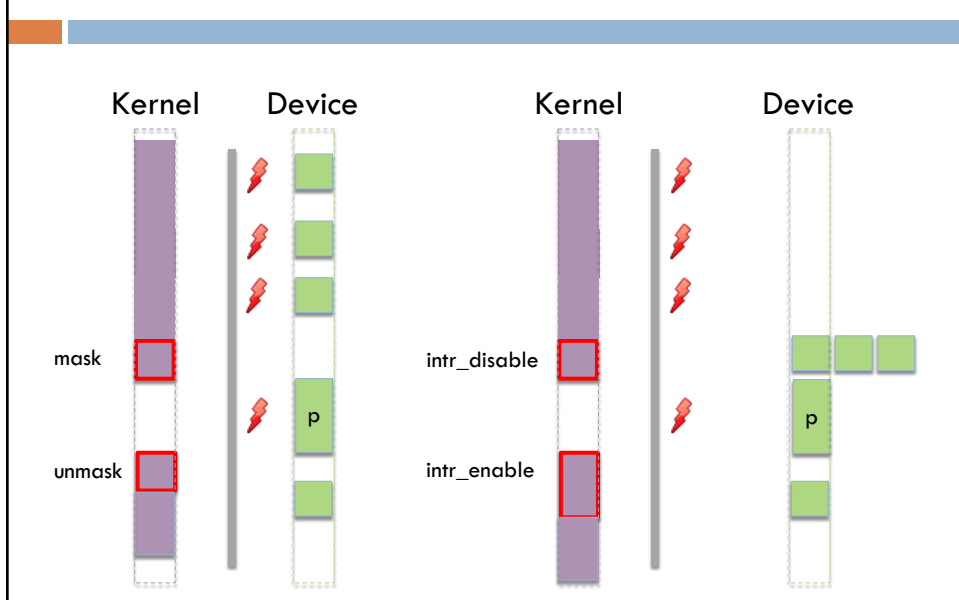
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# Interrupt Models



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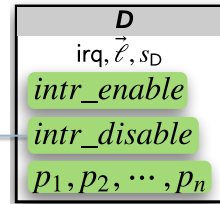
# New HW Interrupt Model



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## Semantics of *intr\_disable*

- Scans external events.
- Recursively performs the environmental transition.
- Synchronizes unhandled interrupts.



details in the paper

DISABLENOINTR: Disable with no unhandled interrupt

$$\frac{(e, \ell_i) = \text{next}(\ell^{env}, \ell_i) \quad s_{\text{tmp}} = \delta^{env}(s, e) \quad s'.irq = \text{false} \quad s' = s[\text{Flag} \leftarrow 0]}{\text{intr\_disable}(s, \ell_i, \ell^{env}) = (s', \ell_i)}$$

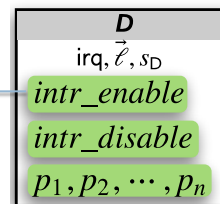
DISABLEINTR: Disable with unhandled interrupts

$$\frac{(e, \ell_i) = \text{next}(\ell^{env}, \ell_i) \quad s' = \delta^{env}(s, e) \quad s'.irq = \text{true} \quad (s'', \ell_i'') = \text{intr\_handler}(s', \ell_i, \ell^{env}) \quad (s''', \ell_i''') = \text{intr\_disable}(s'', \ell_i'', \ell^{env})}{\text{intr\_disable}(s, \ell_i, \ell^{env}) = (s''', \ell_i''')}$$

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## Semantics of *intr\_enable*

- Recursively discharges pending interrupts.
- Delayed interrupts that occur while the interrupt is disabled.



details in the paper

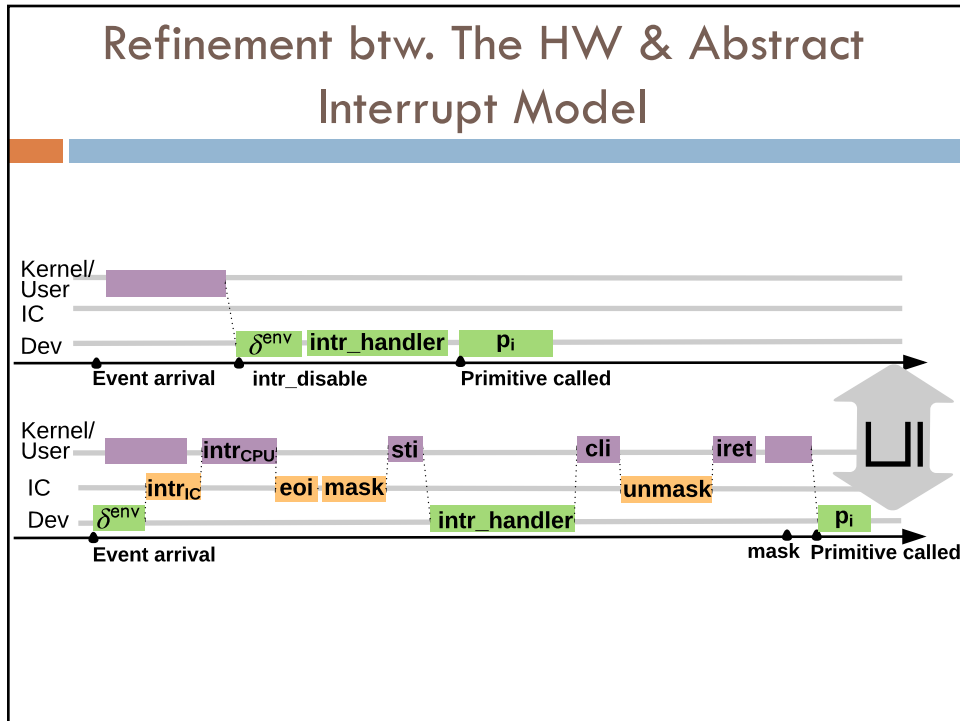
ENABLENOINTR: Enable with no pending interrupt

$$\frac{s.irq = \text{false} \quad s' = s[\text{Flag} \leftarrow 1]}{\text{intr\_enable}(s, \ell_i, \ell^{env}) = (s', \ell_i)}$$

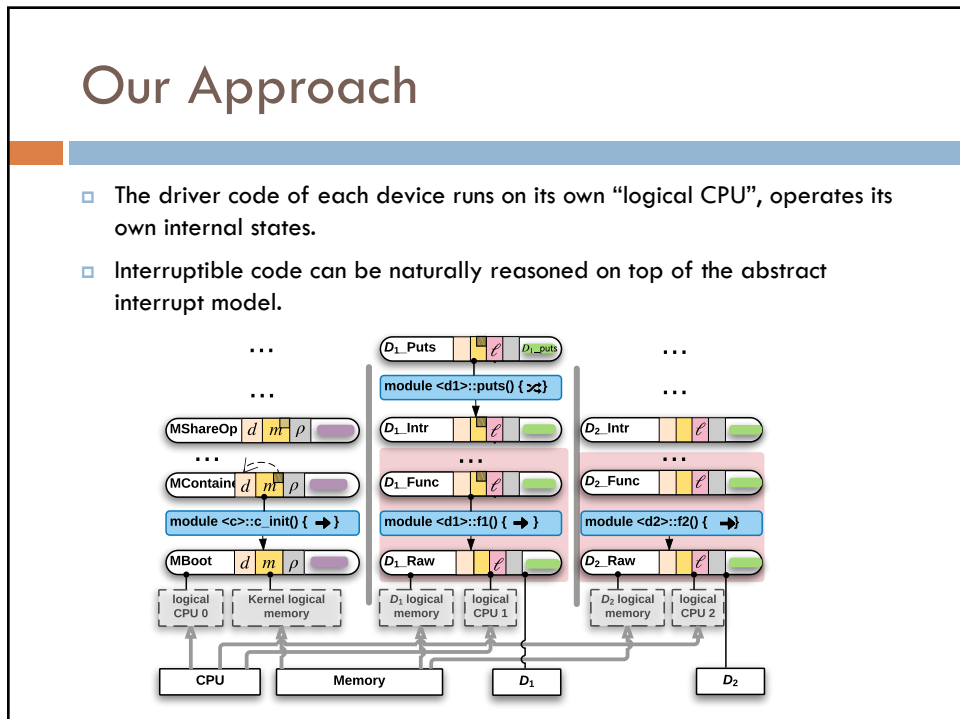
ENABLEINTR: Enable with pending interrupts

$$\frac{s.irq = \text{true} \quad (s', \ell_i') = \text{intr\_handler}(s, \ell_i, \ell^{env}) \quad (s'', \ell_i'') = \text{intr\_enable}(s', \ell_i', \ell^{env})}{\text{intr\_enable}(s, \ell_i, \ell^{env}) = (s'', \ell_i'')}$$

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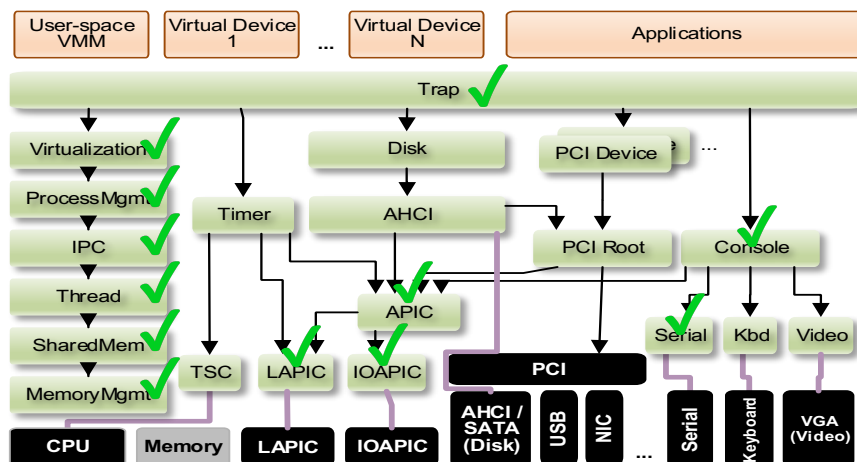
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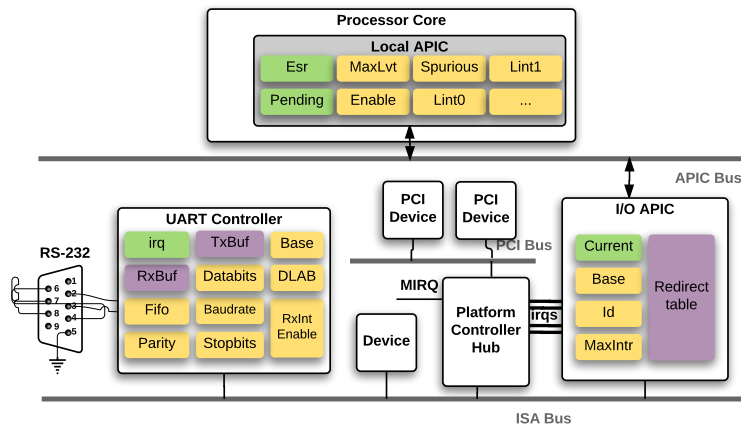
## Interruptible mCertikOS with Drivers



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## Case Study: Modeling HW Devices

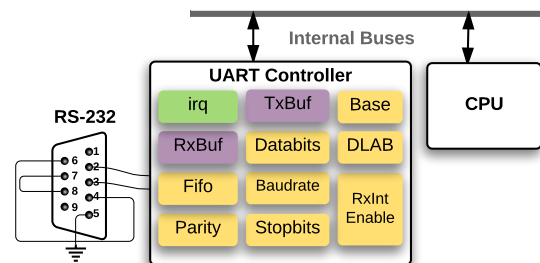
- Serial Port, I/O APIC, Local APIC, CPU interrupt handling.



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## Case Study: Serial Device

- States: see figure
- Transitions: `serial_trans_env` + `serial_trans_IO`
- Read/Write primitives: `serial_read` / `serial_write`



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## Serial Interrupt Handler

```

1 void serial_intr () {
2   unsigned int hasMore;
3   int t = 0;
4   hasMore = serial_getc ();
5   while (hasMore && t < CONSOLE_BUFFER_SIZE) {
6     hasMore = serial_getc ();
7     t++;
8   }
9 }

1 unsigned int serial_getc () {
2   unsigned int rv = 0;
3   unsigned int rx;
4   if (serial_exists()) {
5     if (serial_read(COM1 + COM_LSR, BIT1) % 2 == 1)
6       {
7         rx = serial_read(COM1 + COM_RX, M_ALL);
8         cons_buf_write(rx);
9         rv = 1;
10        }
11    }
12   return rv;
13 }

```

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## Serial Driver

```

1 void serial_puts(char * s, int len) {
2   int i = 0;
3   while (i < len && s[i] != 0) {
4     serial_intr_disable ();
5     serial_putc (s[i]);
6     serial_intr_enable ();
7     i++;
8   }
9 }

1 void serial_putc (unsigned int c) {
2   unsigned int lsr = 0, i;
3   if ( serial_exists() ){
4     for (i = 0; !lsr && i < 12800; i++) {
5       lsr = serial_read(0x3FD) & 0x20;
6       delay();
7     }
8     serial_write (0x3F8, c);
9     ...

```

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## What We Have Proved

- Total functional correctness.
- Safety.
- *Contextual refinement* between the lowest and the top level abstract machine:
 
$$\forall P, \llbracket K \bowtie P \rrbracket_{x86} \sqsubseteq \llbracket P \rrbracket_{mCertiKOS}$$
- Data invariants:
  - Console's circular buffer is always well-formed.
  - Interrupt controller states are always consistent.
- The framework also ensures that:
  - No code injection attacks, buffer overflow, integer overflow, null pointer access, etc.

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## Size of TCB and Spec/Proof

- In the TCB
  - X86 hardware model
  - Hardware device/interrupt model (510 LOC)
  - System call specification (126 LOC)
  - Bootloader
  - Coq proof checker
  - Pretty-printing phase of the CompCert compiler
- Rest of the spec/proof (about 20k LOC)
  - Intermediate and auxiliary specifications and definitions
  - Coq proof scripts

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## Conclusion

- Compositional framework for building certified interruptible kernel with device drivers.
  - Certified abstraction layers with multiple logical CPUs.
  - An abstraction-layer-based approach for expressing interrupts.
- The first formally verified interruptible OS kernel with device drivers.
- Extensions:
  - Other drivers
  - Concurrency
  - Larger kernel

